

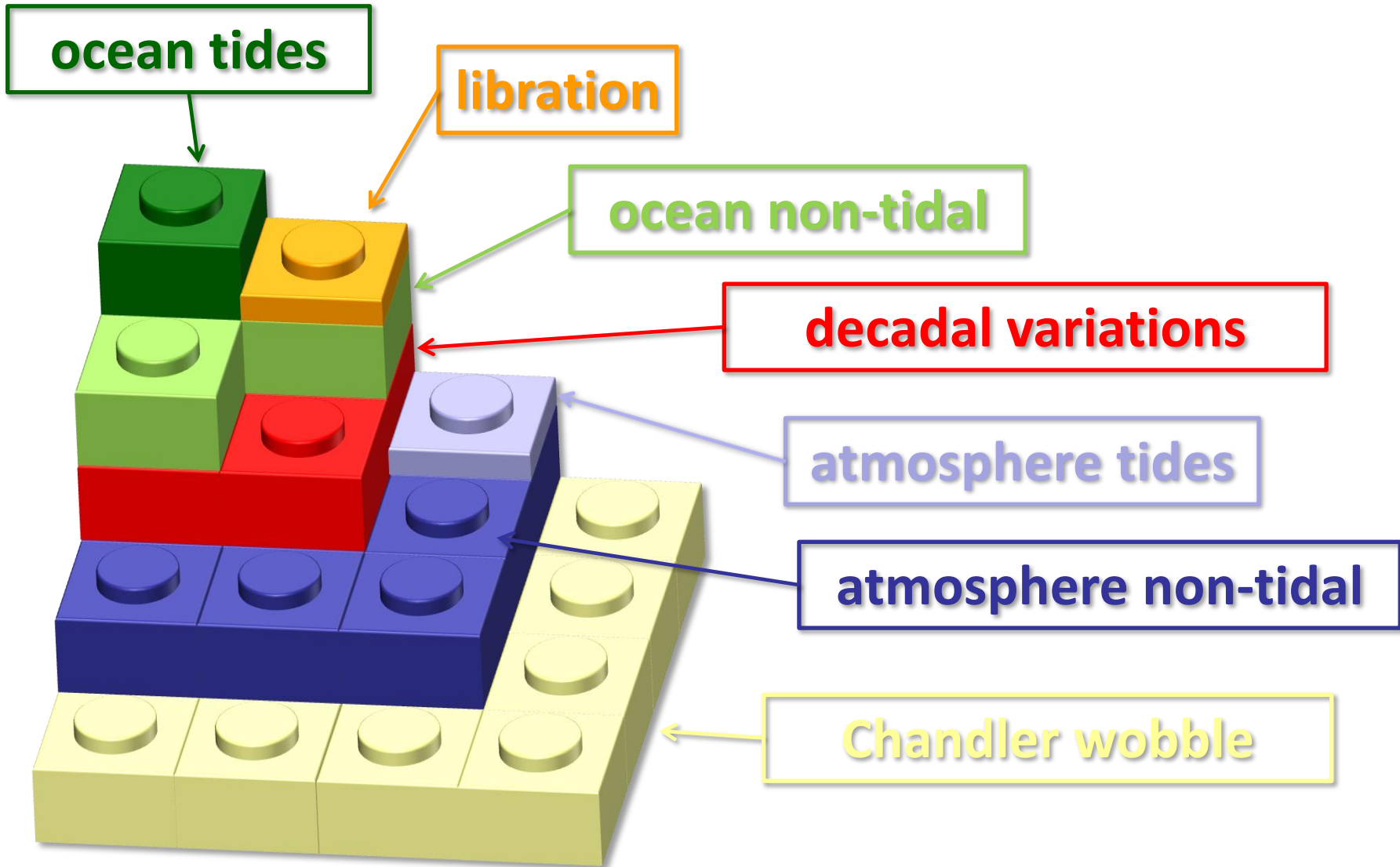
High-frequency signals of oceans and atmosphere in Earth rotation

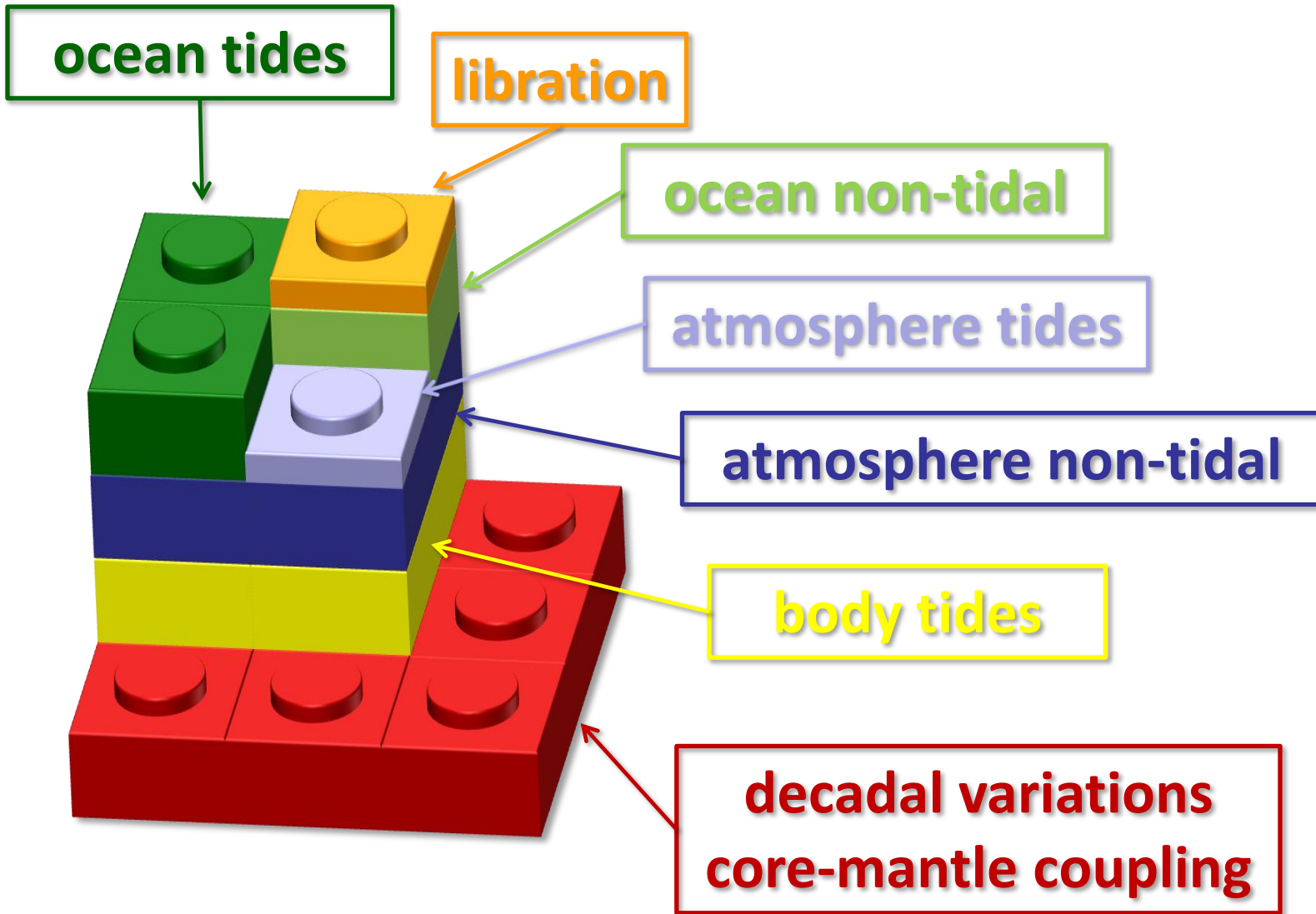
Sigrid Böhm

Tobias Nilsson

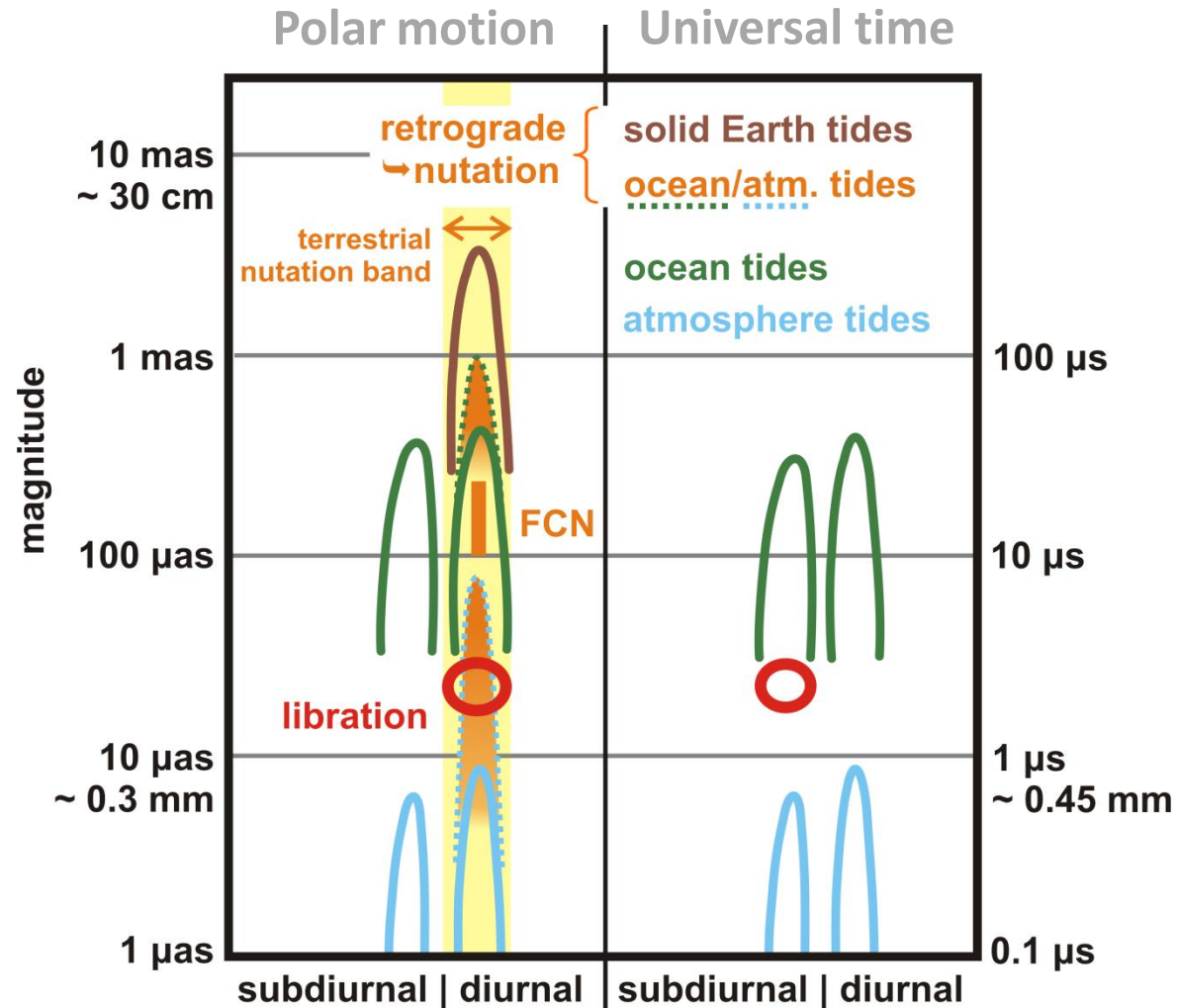
Michael Schindelegger

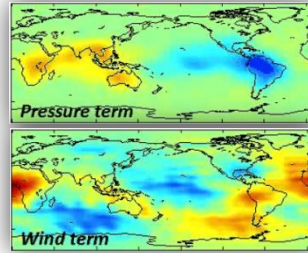
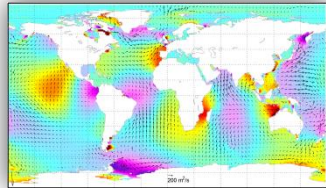
Harald Schuh





- Ocean tides
 - Q1, O1, P1, K1, N2, M2, S2, K2
- Atmosphere tides
 - S1, S2
- Effect of lunisolar torque on triaxial Earth
 - PM: O1, P1, K1
 - UT1: M2, S2





predicted from ...

ocean tide models

numerical weather model data

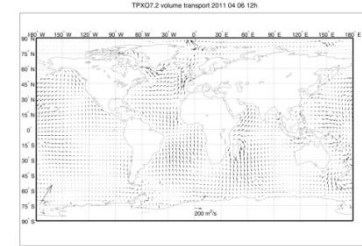
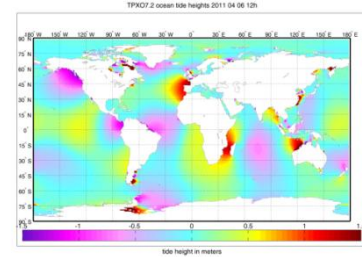
theory tidal potential

measured by ...

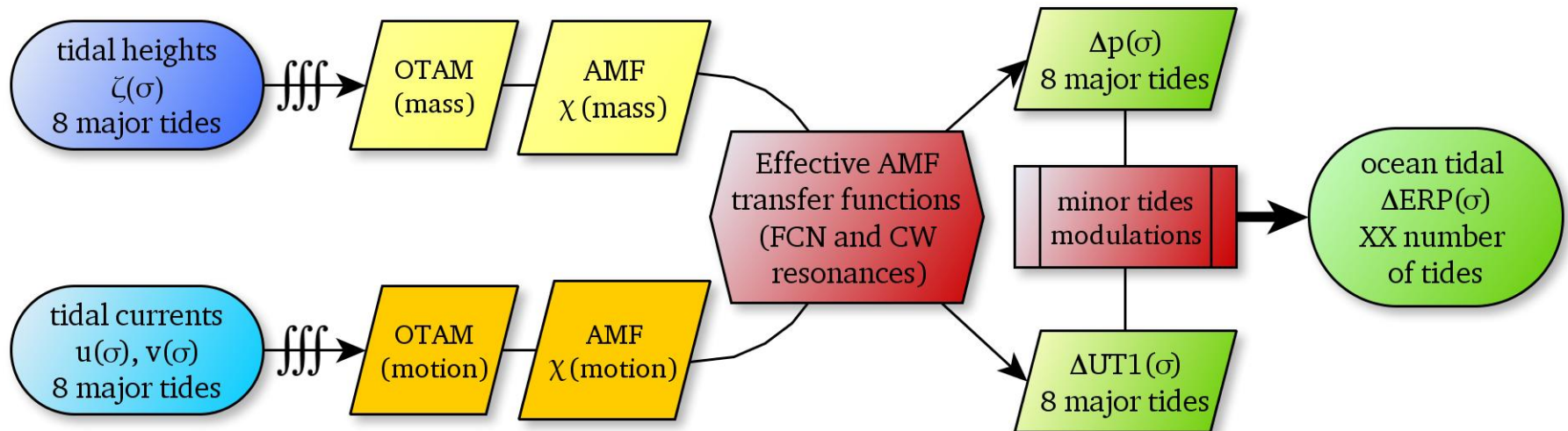
VLBI, GNSS, SLR, ringlaser ...

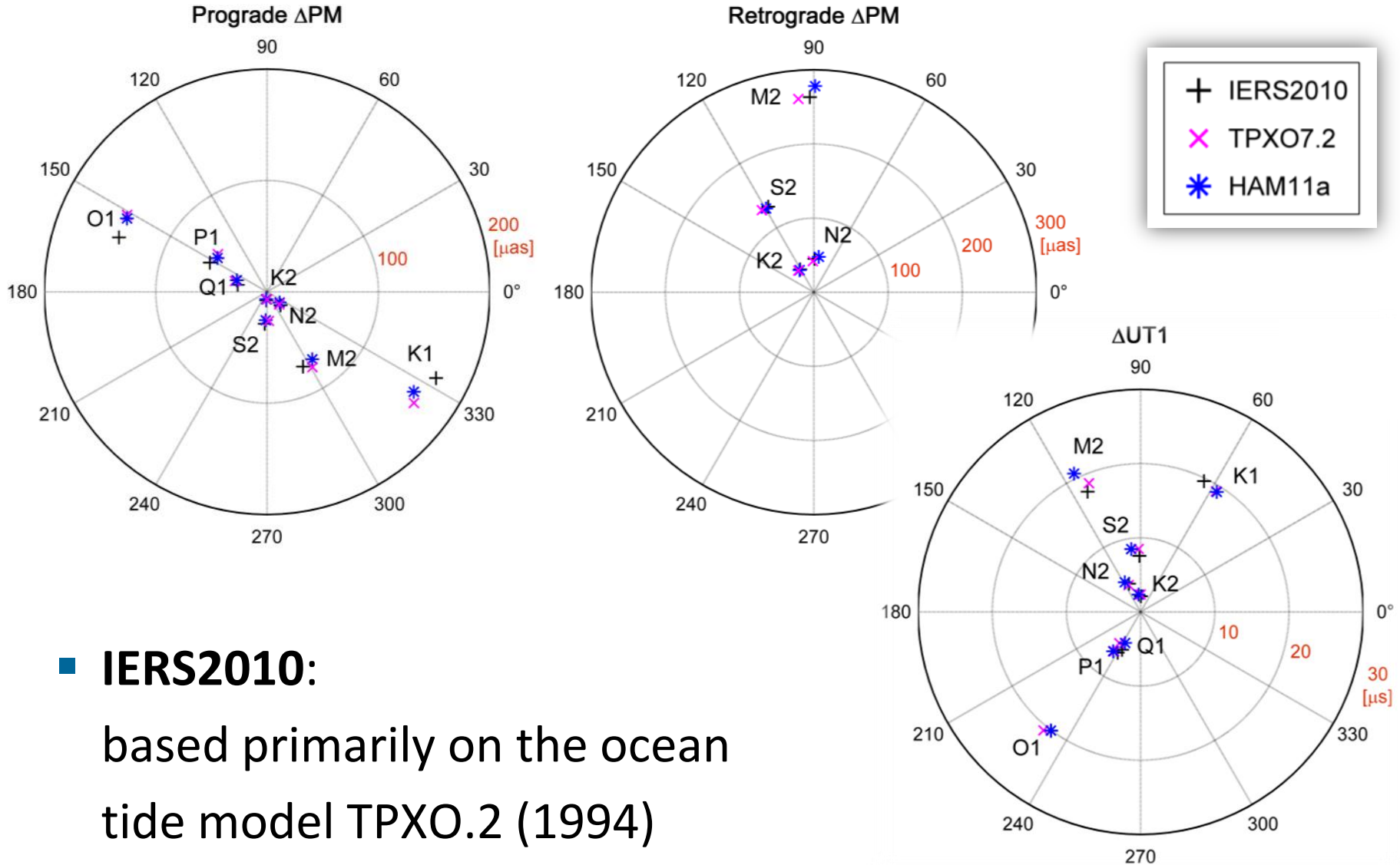
- Global grids of complex amplitudes of tidal heights and current velocities

- **TPX07.2**: Oregon state university (2010)
- **HAMTIDE11a**: University of Hamburg (2011)



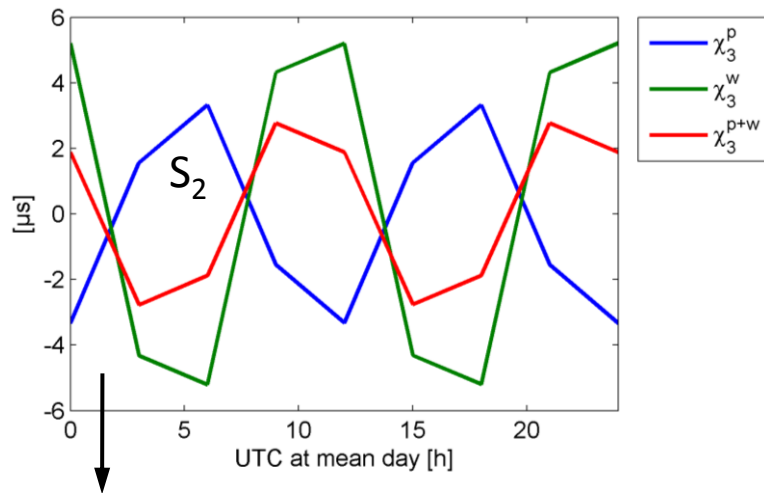
data-assimilative hydrodynamic models







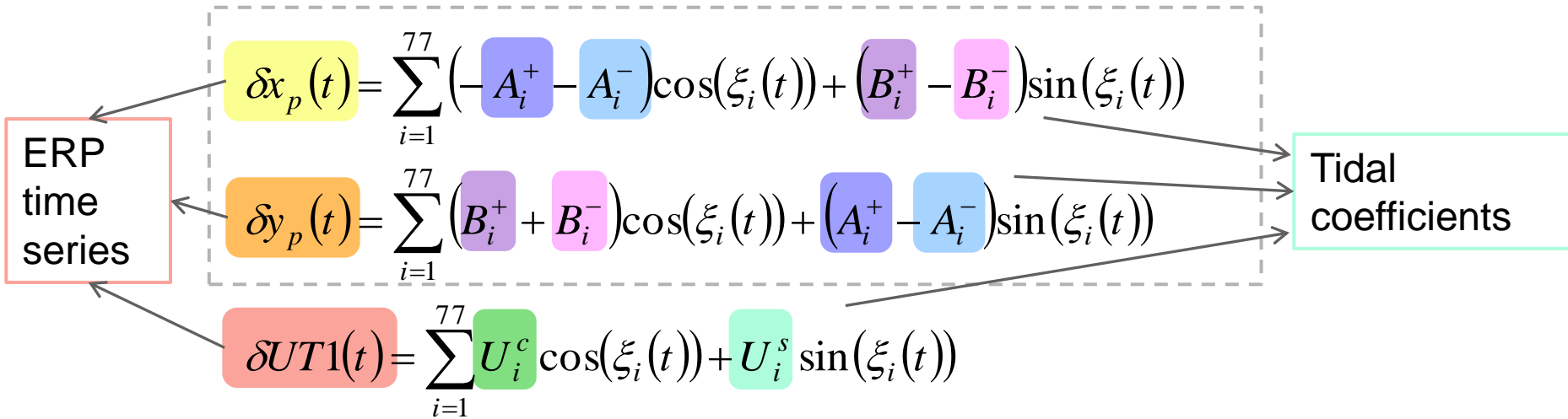
- Earth rotation excitation at daily and subdaily periods, investigated with different sets of AAM functions (from different ECMWF data classes)
 - Polar motion: amplitudes of S1 and S2 $\sim 1 \mu\text{s}$
 - UT1: amplitudes of S1 and S2 $< 0.5 \mu\text{s}$



Pressure and wind terms partly balance each other, total net effect small

- Models of S1 and S2 are strongly dependent on the atmospheric model and the considered data time interval
- Amplitudes are small: pressure and wind effects, decisive for Earth rotation variations counterbalance each other.
- Poster XL121: Schindelegger et al.

- Option 1: from highly resolved (1-2 h) ERP time series
 - 1st step: estimate celestial pole offsets (cpo) for all sessions
 - 2nd step: re-introduce cpo, fix nutation, estimate ERP with hourly resolution
 - 3rd step: remove low-frequency signal from the ERP time series, estimate amplitudes of selected periods in a least squares adjustment



$$\xi_i(t) = \sum_{j=1}^6 a_{ij} \alpha_j(t)$$

a_{ij} ... 6 integer multipliers for each tide i

α_j ... 5 Delaunay variables $l, l', F, D, \Omega + (\text{GMST} + \pi)$

as used in the IERS Conventions

- Option 2: from demodulated ERP (complex demodulation technique, Herring & Dong (1994), Brzezinski (2012))
 - celestial pole offsets (nutation) can be estimated!
 - alternative ERP parameterisation:

$$\begin{bmatrix} x_p(t) \\ y_p(t) \end{bmatrix} = \sum_{\substack{k=-N \\ k \neq -1}}^N \begin{bmatrix} x_k(t) \\ y_k(t) \end{bmatrix} \cos(k\phi(t)) + \begin{bmatrix} y_k(t) \\ -x_k(t) \end{bmatrix} \sin(k\phi(t))$$

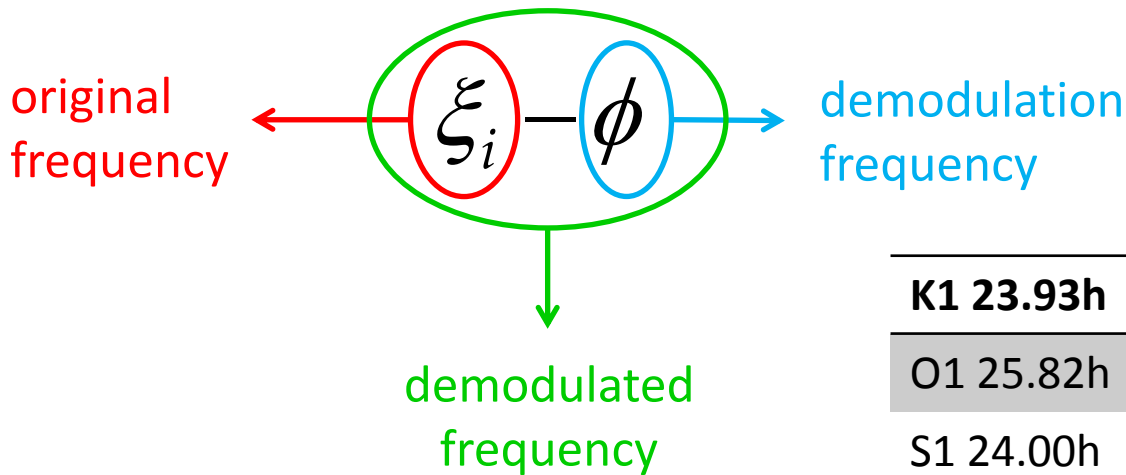
$$UT1(t) = \sum_{k=0}^N u_k^c(t) \cos(k\phi(t)) + u_k^s(t) \sin(k\phi(t)) \quad \phi = GMST + \pi$$

$$k = 0 \Rightarrow \begin{bmatrix} x_0(t) \\ y_0(t) \end{bmatrix} \underbrace{\cos(0)}_1 + \cancel{\begin{bmatrix} y_0(t) \\ -x_0(t) \end{bmatrix} \underbrace{\sin(0)}_0}$$

low frequency variations

$k = 1 \dots 4$ (diurnal, semidiurnal, terdiurnal, quarterdiurnal band)

- Option 2: from demodulated ERP (complex demodulation technique)
 - preserves the amplitudes of periodic signals but shifts the frequencies
 - E.g. diurnal frequency band:



K1 23.93h	→	infinity
O1 25.82h	→	13.66 days
S1 24.00h	→	365.25 days

Tidal coefficients

$$\underbrace{\delta UT1(t)}_{\text{diurnal}} = \cos \phi \cdot \sum_{i=1}^n \underbrace{[U_i^s \sin(\xi_i - \phi) + U_i^c \cos(\xi_i - \phi)]}_{u_1^c(t)} + \sin \phi \cdot \sum_{i=1}^n \underbrace{[U_i^s \cos(\xi_i - \phi) - U_i^c \sin(\xi_i - \phi)]}_{u_1^s(t)}$$

demodulated UT1 time series

- Option 3: within a global solution
 - Accumulate single session normal equations
 - Estimate tidal terms directly together with other parameters such as station positions

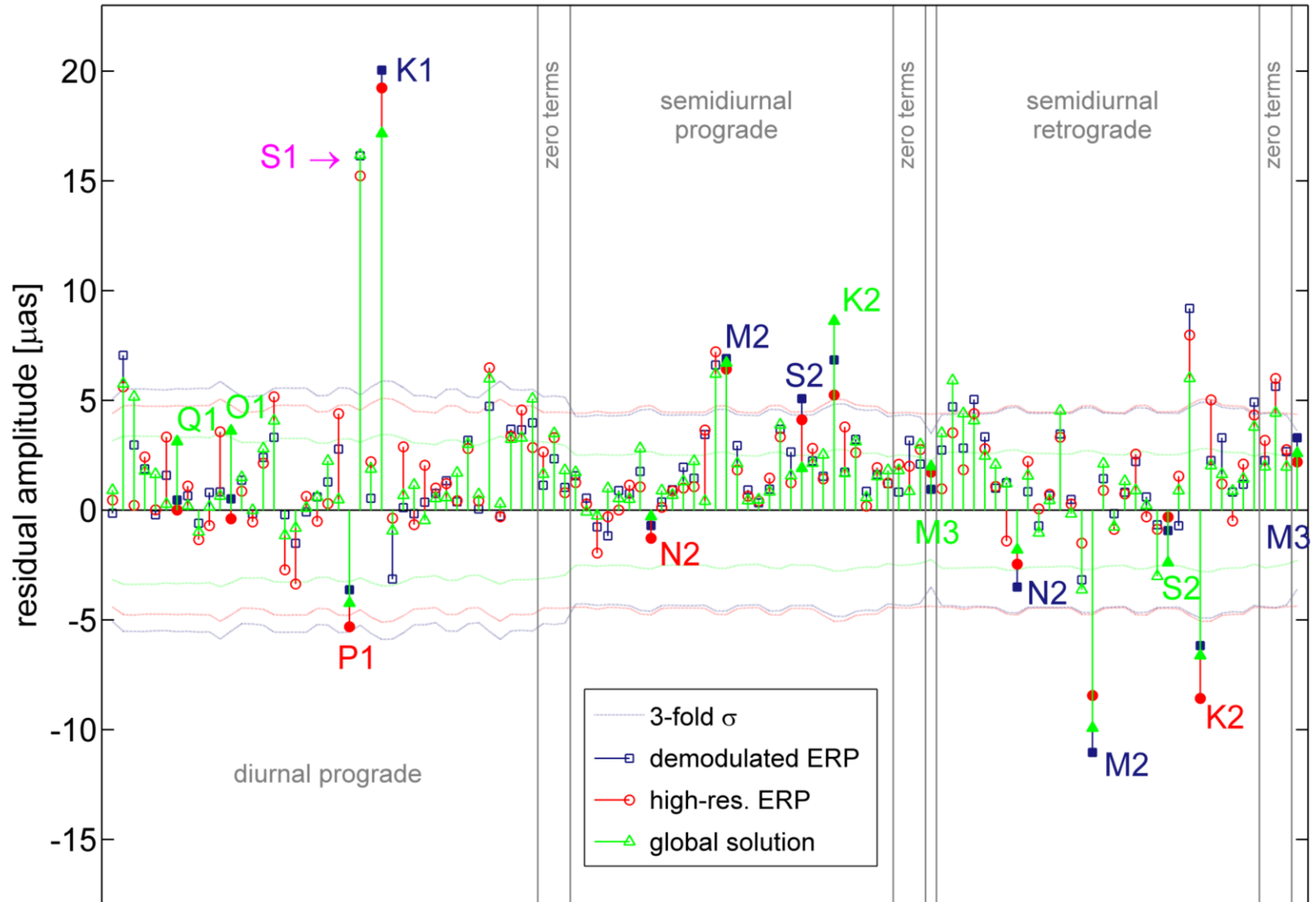
- 3 sets of tidal amplitudes
 - Vienna VLBI Software VieVS: VLBI data 1984-2010
 - Polar and spin libration considered a priori
 - 40+3 diurnal, 30+3 semidiurnal, 1 terdiurnal (M3) tide/s

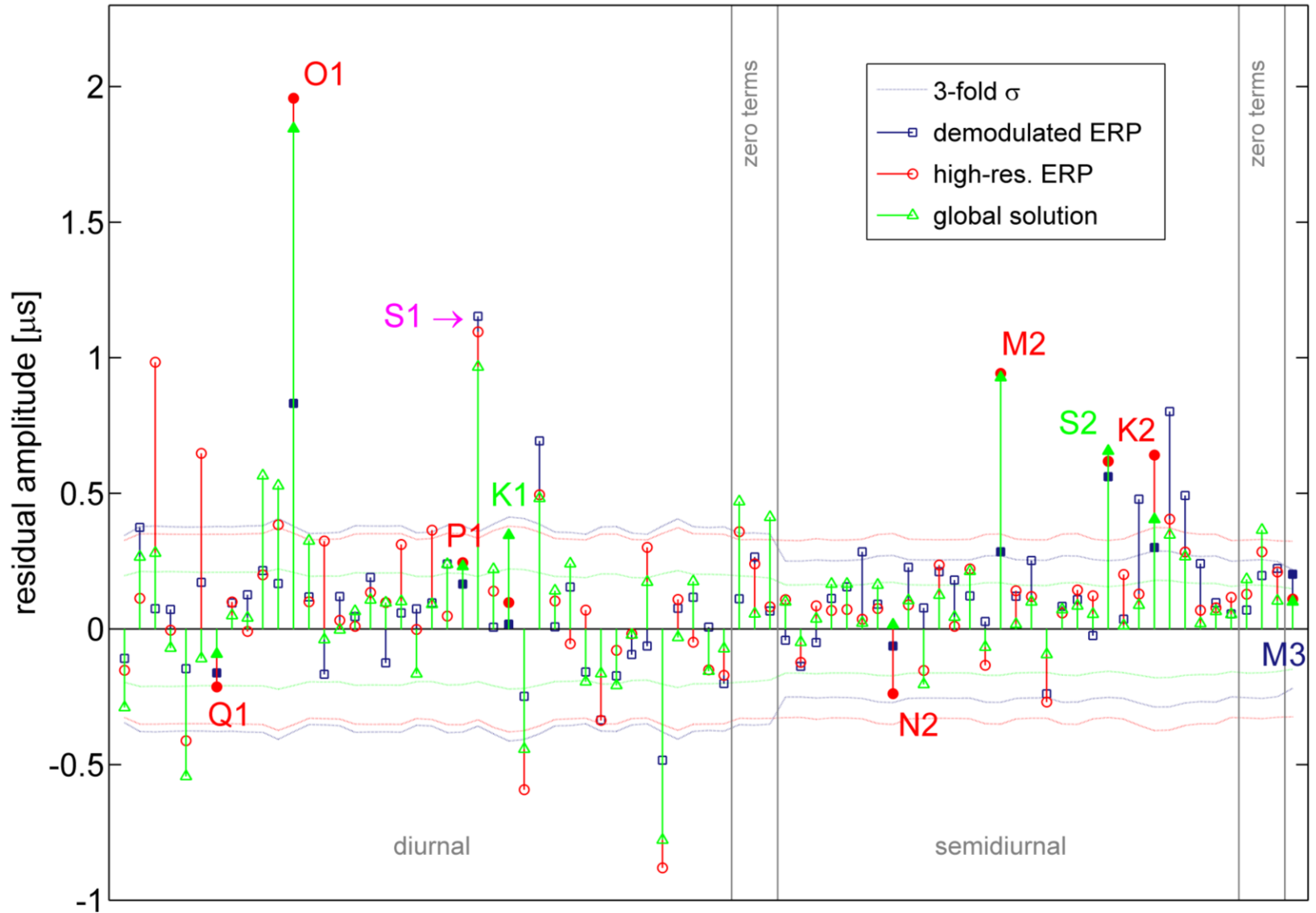
Option 1: highly resolved ERP time series

Option 2: demodulated ERP time series

Option 3: global solution







Model	IERS2010	TPXO7.2	HAM11a	VieVS 3	Artz et al.	ERP	
IERS2010		4.05	3.47	4.60	4.90		polar motion [μas]
TPXO7.2	0.32		3.07	4.21	4.53		
HAM11a	0.45	0.30		5.31	5.86		
VieVS 3	0.38	0.35	0.41		2.31		
Artz et al.	0.38	0.35	0.43	0.16			
ERP	universal time [μs]						

ocean tide models

VLBI global solution

empirical model from a VLBI global solution, derived with Calc/Solve Software: Artz et al. (2011), *J Geod.*

* calculated only from the terms which are part of this model

- VLBI estimates show better mutual agreement than ocean tide models
- ERP variations based on TPXO7.2 fit best to the VLBI values, for polar motion as well as for UT1

- More recent ocean tide models do not necessarily agree better to empirical tidal ERP terms.
- There is room for improvement – on the part of the modeling procedure?
- Extension with S1 tide from ocean tide models could help.
- S1 and S2 from atmospheric models should be interpreted with caution as they are strongly dependent on the used model and the considered data time interval.
- Combined analysis of VLBI and ring laser data
 - Poster XL 119, Nilsson et al.

