Impact of troposphere modeling on GNSS satellite antenna phase center pattern estimation

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ζ	n_{GPS}	
0	0.0	
10	2.4	
20	4.7	
30	6.9	
40	8.8	
50	10.6	
60	11.9	
70	12.9	
80	13.6	
90	13.8	





ζ	n_{GPS}	n_{GLO}
0	0.0	0.0
10	2.4	2.5
20	4.7	4.9
30	6.9	7.2
40	8.8	9.2
50	10.6	11.0
60	11.9	12.4
70	12.9	13.4
80	13.6	14.1
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A zenith-angle-dependent bias in the troposphere model may be compensated by the estimated satellite antenna phase center pattern.

	Satellite antenna phase center		
IGS08.ATX	pattern	offset	
GPS	from IGS05.ATX	from repro1 and final	
	(GFZ,TUM)	(CODE,ESA,GFZ,MIT,NRCan)	
	NMF	GMF	



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GLONASS	from GLONASS-repro	from GLONASS-repro	
	(CODE,ESA)	(CODE,ESA)	
	GMF	GMF	



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GPS IIF	from GLONASS-repro	from GLONASS-repro
	(CODE,ESA)	(CODE,ESA)
	GMF	GMF
GLONASS	from GLONASS-repro	from GLONASS-repro
	(CODE,ESA)	(CODE,ESA)
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	(CODE,ESA)	(CODE,ESA)
	GMF	GMF

CODE has started to use VMF1 for its operational final and rapid products in October 2010.





How do different troposphere models affect the satellite antenna phase center?



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- Which solution compares best with a LEO-derived solution? (independent from troposphere model)



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- What is the impact on ground stations, if the troposphere model is inconsistent with the satellite antenna phase center model?



- observation files \rightarrow weekly normal equation file
 - implicit: satellite orbits, troposphere parameters, Earth rotation parameters
 explicit: coordinates, satellite antenna phase center offsets and patterns
 IGS08.ATX for receiver antenna phase center corrections
 3° elevation mask (in fact: 5°)



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series with different troposphere models:
 VMF1: Vienna Mapping Function ECMWF (Böhm et al., 2006)
 GMF: Global Mapping Function GPT (Böhm et al., 2006)
 NMF: Niell Mapping Function Berg, 1947 (Niell, 1996)



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The cumulative solution has been computed using identical datum stations and same solution intervals: minimum constraint solution w.r.t. IGS08 frame







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Differences between NMF-based estimates and IGS08.ATX values



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Differences between GMF-based estimates and IGS08.ATX values



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Differences between VMF1–based estimates and IGS08.ATX values



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Differences between VMF1– and GMF–based estimates



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n_{GPS} ζ_{Earth}	
2 8.4	
<i>n</i> 4 16.9	
6 25.8	
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10 46.2	
E 12 59.9	
$[] 20^{3} $ 13 69.4	
C 0 15	
≈ 16	
Values given in degree	



















Use of LEOs for GNSS satellite antenna estimation

Advantages:

due to the higher altitude bigger nadir angles may be achieved



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- near-field environment of the antenna onboard the LEO
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Use of LEOs for GNSS satellite antenna estimation

- To compensate the near-field environment antenna phase center maps need to be co-estimated for the LEO-POD.
- These maps are fully correlated with the GPS satellite antenna phase center patterns.
- A combination of several missions is preferable to solve for the GPS satellite antenna phase center patterns.

Antenna phase center map for Jason–2



Differences between Jason-2-based estimates and IGS08.ATX values



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Differences between GRACE A/B-based estimates and IGS08.ATX values



Differences between Jason+GRACE-based estimates and IGS08.ATX values



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Differences between Jason+GRACE-based estimates and IGS08.ATX values





Differences between Jason+GRACE-based estimates and IGS08.ATX values



Differences between Jason-2- and GMF-based estimates



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Differences between Jason+GRACE- and VMF1-based estimates



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Differences between Jason+GRACE–based and GMF–based estimates





Differences between Jason+GRACE–based and VMF1–based estimates



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Differences between Jason+GRACE-based and NMF-based estimates





Influence on the station coordinates

- Four sets of satellite antenna phase center patterns are available:
 - from the VMF1-based cumulative solution
 - from the GMF-based cumulative solution
 - from the NMF-based cumulative solution
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- Repeating the VMF1-based cumulative solution introducing different satellite antenna phase center patterns
- Identical discontinuities and datum stations for the minimum constraint condition
- How do the different sets of satellite antenna phase center patterns influence the coordinate solution?



Influence on the station positions

Position differences between the solutions using *satellite*—specific GMF— and VMF1—based satellite antenna pattern



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Influence on the station positions

Position differences between the solutions using *satellite*—specific Jason+GRACE— and VMF1—based satellite antenna pattern



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Height differences between the solutions using *satellite*—specific GMF— and VMF1—based satellite antenna pattern





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Height differences between the solutions using *satellite*—specific NMF— and VMF1—based satellite antenna pattern





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Height differences between the solutions using *satellite*—specific Jason+GRACE— and VMF1—based satellite antenna pattern





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Height differences between the solutions using *block*-specific GMF- and VMF1-based satellite antenna pattern





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Height differences between the solutions using *block*-specific NMF- and VMF1-based satellite antenna pattern





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There are small differences for high nadir angles if comparing, e.g., NMF with GMF/VMF1.

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