



# Differences between GPS receiver antenna calibration models and influence on geodetic positioning

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## Outline

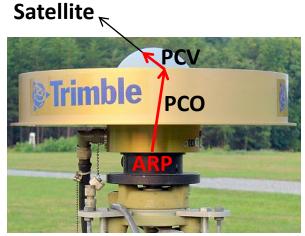
- Individual antenna calibration methods
- Methodology
  - Precise Point Positioning
  - Data sets
- Impact on computed station position
- Summary and conclusions





- Computed GPS station position: Antenna Reference Point (ARP)
- GPS signal measured at the virtual phase center of the receiving antenna
- Phase center corrections = Difference between ARP and phase center of the antenna
- Determined by the calibration and divided in 2 parts:
  - Phase center offset (PCO): independent of satellite position
  - Phase center variation (PCV): depend on the azimuth and elevation of the satellite over the antenna
    Satellite

#### $PCC(\alpha,z) = PCO + PCV(\alpha,z)$





#### **Individual calibration methods**



#### **Robot calibrations**



➡ Geo++(D)
Also NGS(USA), Ife(D), SendStadt
Berlin(D)

#### Anechoic chamber calibrations





#### Individual calibration methods



Robot Calibrations	Anechoic chamber calibrations	
Use real GNSS signals	Use generated sine wave	
Only observed signals	Any frequency	
GNSS receiver	Vector Network Analyzer	
Multipath mitigated by intelligent positioning sequence	Multipath mitigated by the chamber	
Used to generate type mean calibrations in the IGS	Can be used to generate type mean calibrations since the igs08.atx	



#### How to compare 2 calibrations



#### $\Delta \mathsf{PCC}(\alpha, z) = (\mathsf{PCO}_1 - \mathsf{PCO}_2) + (\mathsf{PCV}_1(\alpha, z) - \mathsf{PCV}_2(\alpha, z))$

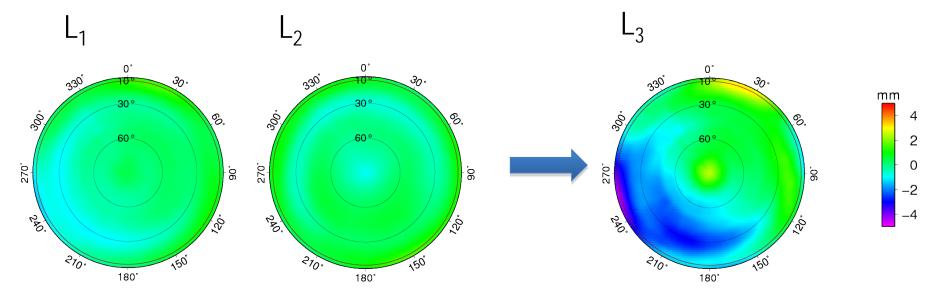
- But PCV are not aligned:
  - Geo++: Zenith PCV = 0
  - Uni-Bonn: PCV = direct phase measurement
- To compare:
  - Shift Uni-Bonn PCC ->Zenith PCV= 0
  - PCC( $\alpha$ ,z) equivalent to PCC( $\alpha$ ,z) + constant for all directions (for positioning)
- Adding a constant: no position offset
  - Only station clocks affected
  - Equivalent to adding cable length



## Individual calibration on L<sub>3</sub>



• Differences of PCC between Geo++ and Uni-Bonn calibrations for a Trimble antenna on  $L_1$  and  $L_2$  and the resulting  $L_3$  calibration



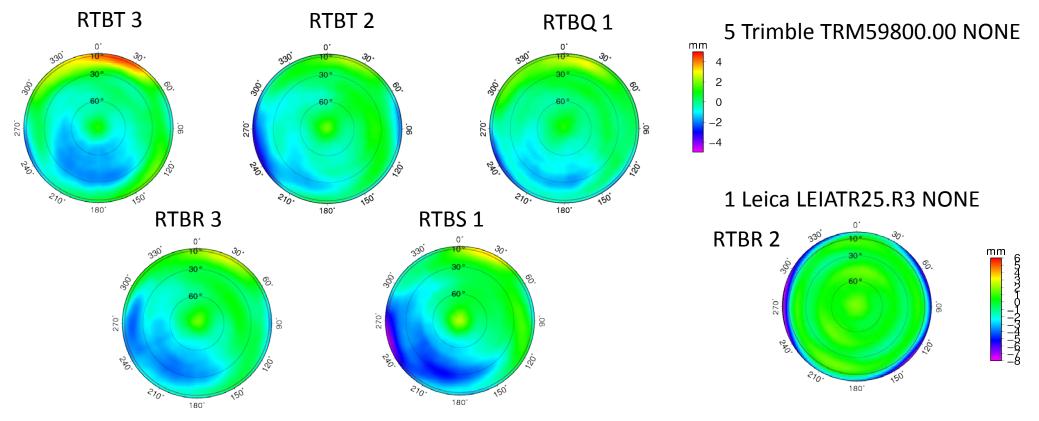
- $\bullet$  Differences on  $L_1$  and  $L_2$  at the mm level but amplified in  $L_3$
- In this study: only L<sub>3</sub> used





#### Individual calibration models PCC differences between Geo++ and Uni-Bonn

- Six antennas installed at ROB.
- Each individually calibrated by both GEO++ and Uni-Bonn.



• What is the impact of the calibration model on computed station position ?





#### Individual calibration models PCO differences between Geo++ and Uni-Bonn

- Six antennas installed at ROB.
- Each individually calibrated by both GEO++ and Uni-Bonn.

Station	North ∆PCO (mm)	East ∆PCO (mm)	Up ∆PCO (mm)*
RTBR 2	0.1	0.0	8.3
RTBT 2	0.7	1.0	-5.3
RTBT 3	1.4	0.6	-6.5
RTBQ 1	1.3	0.5	-6.3
RTBR 3	1.2	1.0	-5.0
RTBS 1	1.5	1.4	-3.7

(\*) PCO of Uni-Bonn adapted for zenith PCV = 0 (approximation: horizontal neglected)

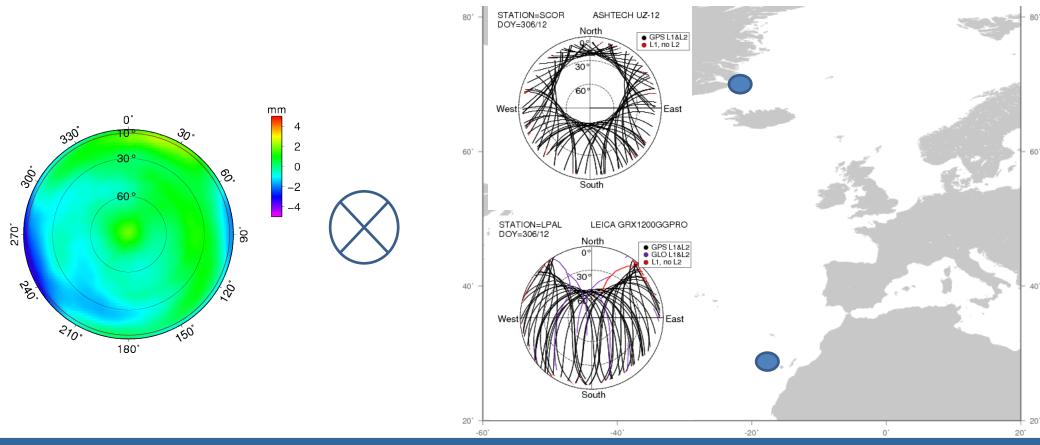
• What is the impact of the calibration model on computed station position ?





## How to estimate the impact on computed station position

- Impact on computed station position not direct:
  - -PCO+PCV (PCC) will affect each satellite differently at each epoch







## How to estimate the impact on computed station position

- Daily RINEX files
- 2 Precise Point Positioning:
  - Identical processing options (10° elevation cut-off, satellite antenna calibrations, orbits and clocks, etc...)
  - 2 different receiver antenna calibrations:
    - Geo++
    - Uni-Bonn
    - ➡ Daily Position offsets

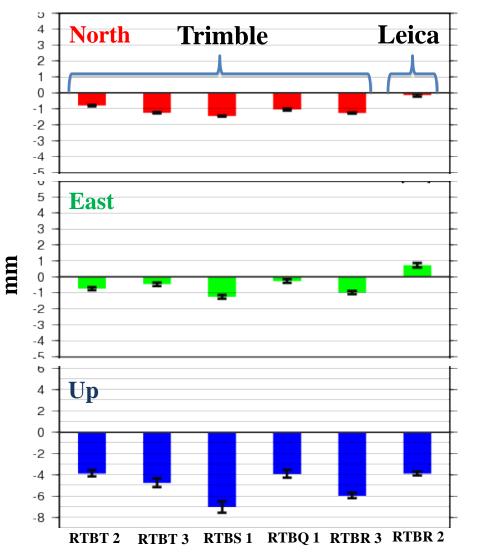
Final position offset = Mean daily position offsets (100 consecutive days)

Rebischung et al., IGS08: the IGS realization of ITRF2008, GPS Solution, vol. 4, issue4, pp. 483-494, 2012.



#### **Position offsets for Brussels**

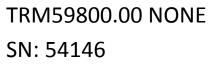


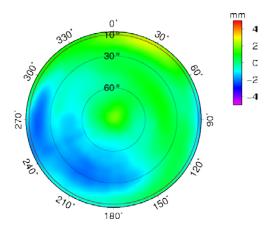


• Horizontal:

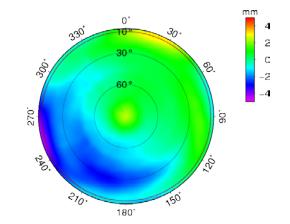
- Trimble: -1 mm in the North and between 0 and -1 mm in the East
- Leica: -0.1 mm in the North and 0 and -1 mm in the East
- Vertical:
  - Between -4 and -7 mm

- On a globally distributed set of stations (IGS08 core stations)
  - Assumption: all stations equipped with the same antenna
  - PPP for 2 antennas (using Geo++ and Uni-Bonn calibrations)
  - Position offset as function of latitude



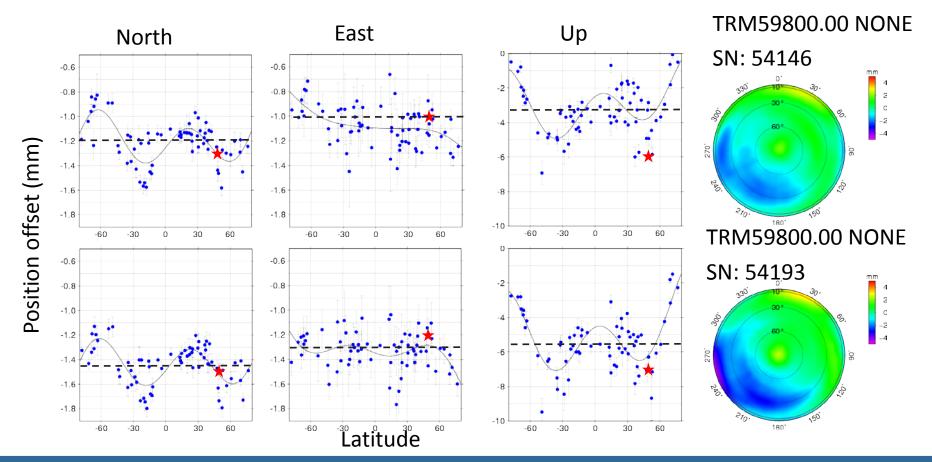


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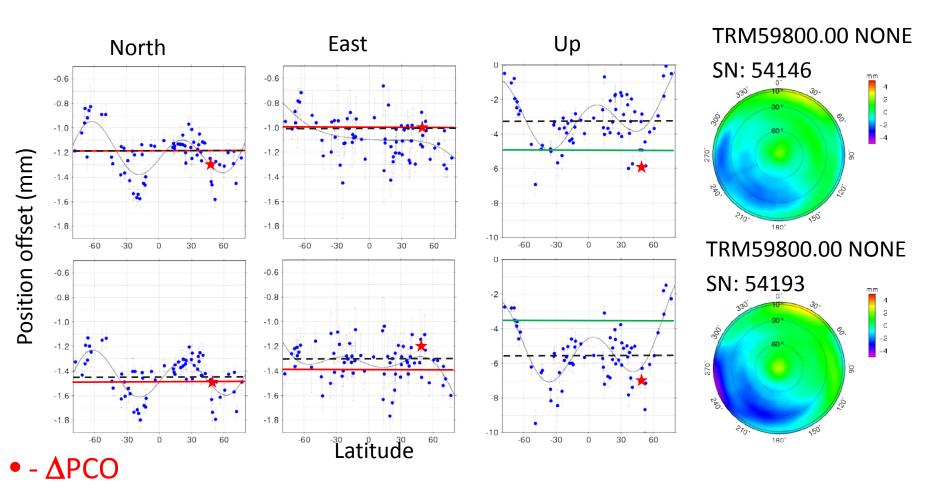


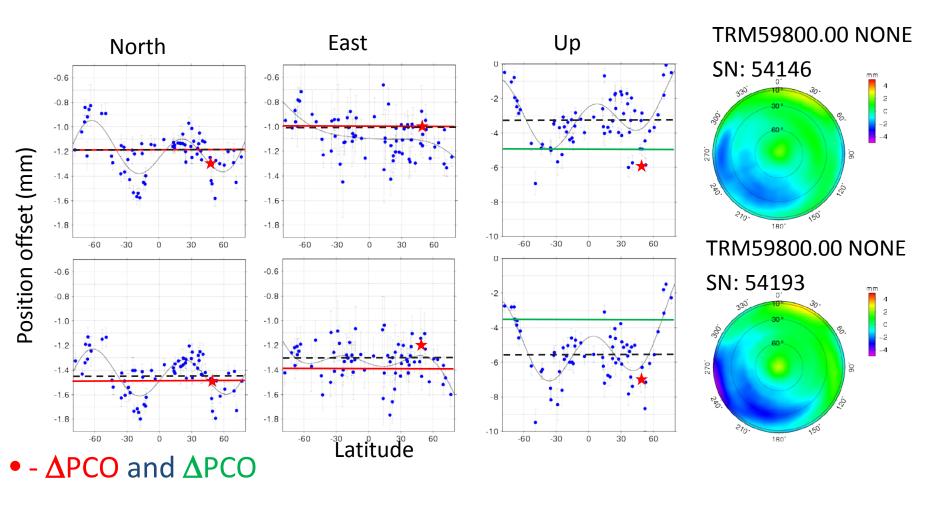
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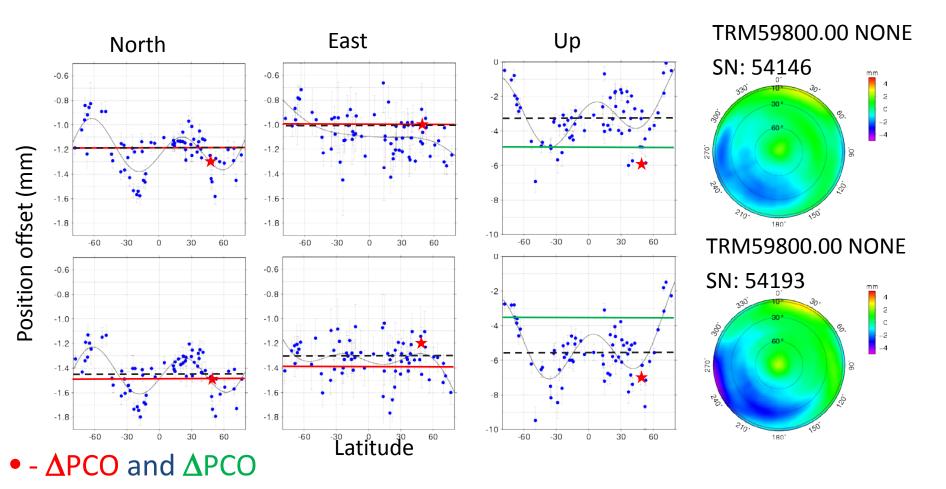
- Latitude dependent model (spherical harmonics) computed
- Horizontal range: 0.4 mm
- Vertical range: 3.5 mm



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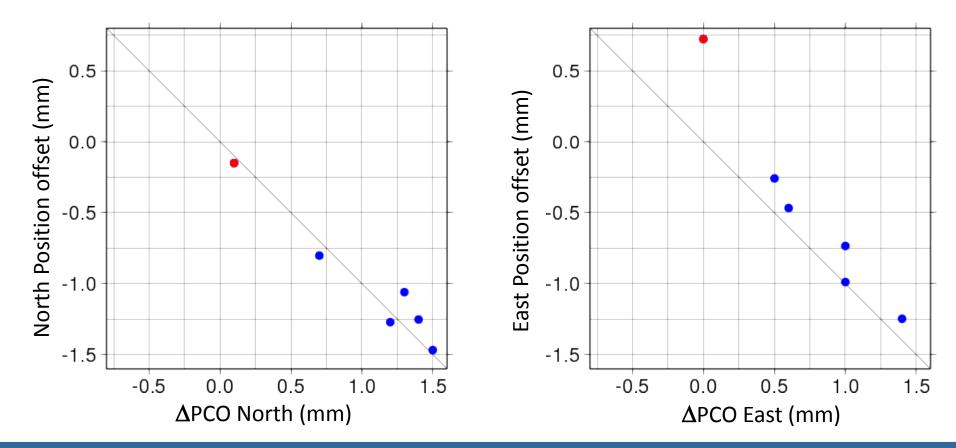
- - $\Delta$ PCO = Mean horizontal offset ±0.1 mm
- Latitude dependency weak
- Up component ?





# Position offsets for Brussels Link with the $\triangle PCO$

- Differences of PCC (PCO+PCV) in all three component
- Link between  $\Delta$ PCO and horizontal component position offset ?
  - Differences between igs08.atx and igs05.atx seem to show similar behaviour









- Station positions computed with Geo++ and Bonn calibrations for 6 antennas in Brussels:
  - -Horizontal position offsets
    - Reach 1 mm and differences between Trimble and Leica antenna
  - -Vertical position offsets
    - Between 3 and 7 mm
- Station positions computed with Geo++ and Bonn calibrations for 2 antennas on a globally distributed set of stations:
  - -Weak latitude dependency position offsets
  - -Horizontal position offsets
    - - $\Delta$ PCO = Mean ±0.1 mm and variations of 0.4 mm to the mean
  - -Vertical position offsets
    - Variations of 3.5 mm to the mean







- Impact of different calibration models on the computed station position not yet fully understood:
  - Up component ?
  - Which level of agreement to reach between receiver antenna calibrations for positioning ?